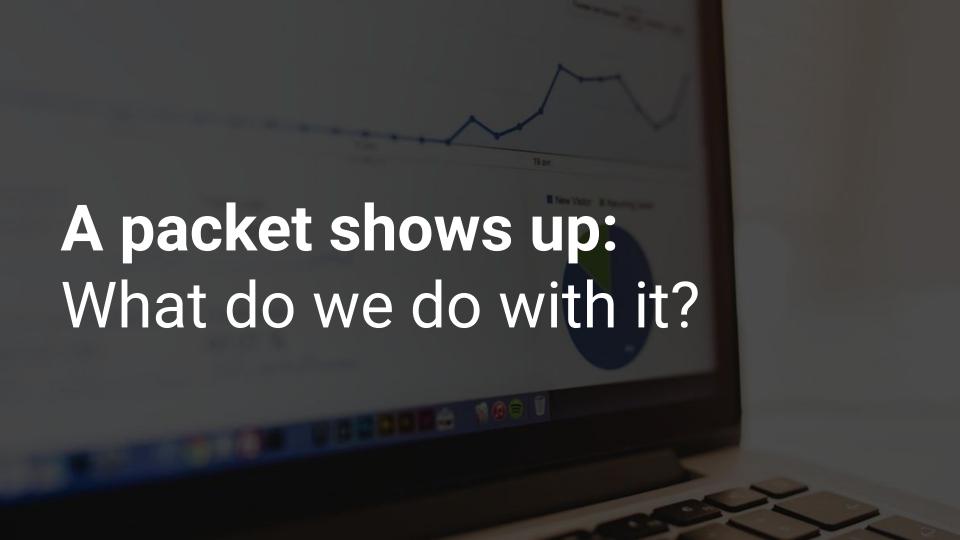
# SDN Control Plane Approaches: A DDlog Retrospective

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### **Network Policy Arithmetic**

Suppose we have N VMs: O(N) policy data.

Pack VMs several to a node: O(N) nodes.

Distribute policy to all nodes:  $O(N^2)$  policy data to distribute.

This is true regardless of how we distribute policy data\*

This is too much. How do we compromise?

#### \*Multicast

If we can multicast the policy data to the nodes, we use only O(N) bandwidth.

I don't know an SDN system that does this.

Research (or references) needed.

### 1. Keep N small

Small N makes O(N<sup>2</sup>) practical.

- Early versions of OVN were OK for N = 2000.
- Most enterprises have 7 or fewer racks.
- The definition of "large" might be larger than one expects.

To some extent this is just "hope it works."

### 2. Chew away at constant factors

- Uniformity.
- Subsetting.
- Compression.
- Simplicity.

#### 3. Reactive control

Early SDN controllers set up one microflow at a time reactively, but:

- Latency
- Load
- Failure

Newer controllers are *proactive*.

OVS internals were once microflow-based; we invented megaflows.

Can we invent megaflows for controllers?

#### 4. Federation

Divide the network into smaller networks.

Use a hierarchy of control.

Networks must be independent or mostly so.

#### 5. Don't change

If the network is static, or only changes rarely, it might not matter that it's expensive to change.

#### 6. Don't centralize

Do we need centralization to accomplish our goals?

- Can a node do what we want with less than O(N) communication?
- Is network virtualization really needed?

### 7. Predictability

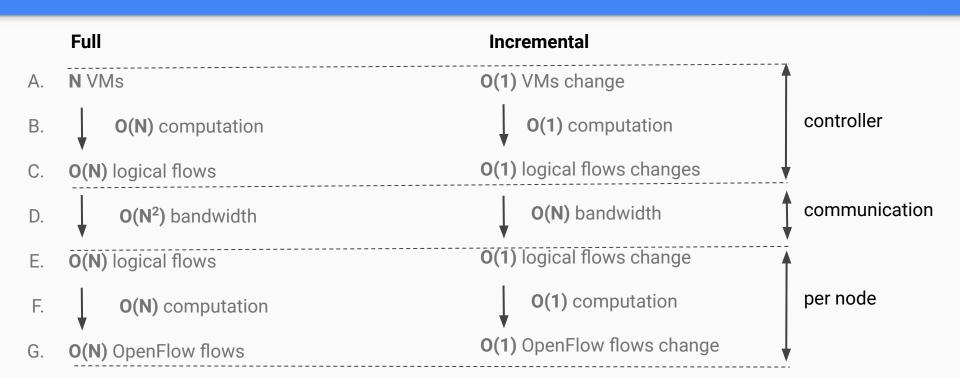
Eliminate the need to distribute per-VM data.

For example, encode VM MAC and IP addresses to imply the security policy and their node of residence.



Can we just compute and transmit changes?

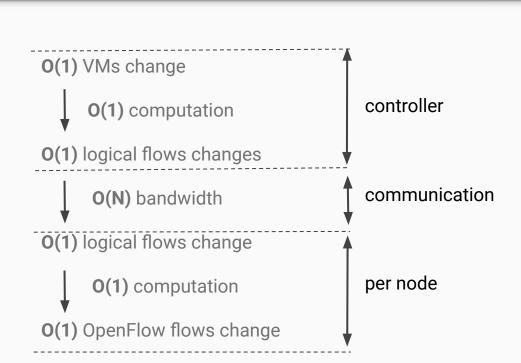
#### **Incremental Control**



# Incremental Control: Assumptions

"Cold start" is fast enough.

- A. Changes are small.
- B. Efficient delta computation.
- C.  $|\Delta Output| = O(|\Delta Input|)$ .
- D. Efficient distribution of incremental changes.
- E. (Ditto)
- F. Efficient generation of OpenFlow deltas.
- G. OVS handles OpenFlow deltas efficiently.



# Incremental Control assumption C: $|\Delta Output| = O(|\Delta Input|)$

If a small input change can yield a much bigger output change, then incremental computation will not be effective.

If such changes happen only rarely, it might still be OK in practice.

OVN load balancers had such a problem: in important cases, changing one in a simple way could affect a hugely disproportionate number of logical flows.

("Load balancer groups" should help.)

# Incremental Computation assumptions B+F: Efficient delta computation

ovn-northd and ovn-controller are complicated and hard to make incremental. We've tried three approaches:

- Ad hoc in C: in ovn-controller (in 2016 by Ryan Moats). This proved too hard to make reliable and was reverted.
- Disciplined in C: in ovn-controller (by Han Zhou). Uses an engine of C callbacks. Still working! Some known issues (based on the tests).
- Automatic in DDlog: in ovn-northd (by Leonid Ryzhyk and others).

# Incremental ovn-northd with DDlog: Best case

From empty, add another router 250 times:

	step 1	<u>step 250</u>	total runtime
C:	.14 s	1.04 s	107 s
DDlog:	.13 s	.15 s	35 s

[\*] https://mail.openvswitch.org/pipermail/ovs-dev/2021-April/381745.html

## Incremental ovn-northd with DDlog: Worst case

Cold start with huge load balancers, then delete each of them:

	wall time	<u>CPU time</u>	RAM
C:	1:20	~87 s	3.8 GB
DDlog:	3:08	187 s	14.2 GB

- DDlog processes each change "twice".
- DDlog can't as easily parallelize processing.
- DDlog indexes data to enable incrementality.

### Other DDlog issues

- New language:
  - Learning
  - Linking
  - o Bugs
  - Tools
- New language paradigm
- Double work for programmers
- Slow builds

### Questions?